GE
Grid Solutions

Multilin 339

Motor Protection System

The Multilin™ 339 is a member of the Multilin 3 Series protective relay platform and has been designed for the protection, control and management of medium voltage motors in industrial applications. The Multilin 339 delivers unparalleled protection, control, diagnostics and communications in an industry leading drawout construction. Providing simplified setup configuration through the use of the Motor Settings Auto-Configurator, advanced graphical diagnostics with the Motor Health Report and support for multiple communication protocols including IEC® 61850, the 339 Motor Protection System provides comprehensive motor protection for most small and medium sized motors.

Key Benefits

- Cost-effective and flexible protection and control device for motors
- Field-proven algorithms and reliable protection to avoid unwanted trips or under-protection
- Ease of use and standardization with simplified motor setup and universal CT inputs
- Enhanced Thermal Model including RTD and current unbalance biasing
- Environmental monitoring system to monitor operating conditions and plan preventative maintenance
- Time stamped event reports, waveform capture, motor start and motor trending
- Powerful security and hierarchical password control for centralized management
- Reduced wiring via remote RTD's using the RMIO module and support for 3 internal RTDs
- Advanced power system and switchgear diagnostics
- Customized motor overload curve Flex curves
- Detailed Motor Health Report with critical data
- Switchgear diagnostics and easy troubleshooting by CT/VT supervision, trip/close circuit supervision and LED/IO Test Mode
- Drawout design simplifies testing, commissioning and maintenance, thereby increasing process uptime
- Flexible communications with multiple ports and protocols allowing seamless integration
- Robust design exceeding industry standards, with Automotive Grade components and advanced testing procedures such as accelerated life cycle testing
- Seamless migration of legacy MII Family relays to the 3 Series platform
- Intuitive configuration software and user-friendly logic configuration tool

Applications

- Protection and control of LV or MV motors of various sizes
- Protection of pumps, conveyors, fans, compressors, and others in process or manufacturing industries. .
- Applications requiring fast and secure communications
- Harsh environments requiring protection against corrosive chemicals and humid environments

imagination at work

Protection & Control

- Thermal model biased with RTD and negative sequence current feedback
- Comprehensive current-based protection including directional elements and Contactor Current Supervision
- Start supervision, inhibit, load increase and mechanical jam
- Underpower/undercurrent and directional power

Metering & Monitoring

- Comprehensive metering
- Programmable oscillography up to 32 samples per cycle and digital states
- SNTP or IRIG-B clock synchronization
- Motor health and switchgear diagnostics including breaker monitoring, CT/VT and close/trip coil supervision
- Relay health diagnostics

Communications

- Front USB and rear serial, Ethernet and fiber ports
- Multiple communication protocols including IEC 61850, IEC 61850 GOOSE, Modbus® TCP/IP, Modbus RTU, DNP 3.0, IEC 60870-5-104, IEC 60870-5-103

EnerVista™ Software

- Simplified setup and configuration
- Strong document management system
- Full featured monitoring and data recording
- Maintenance and troubleshooting tool
- Seamless integration toolkit
- Setting conversion tool for MII Family to 3 Series

Overview

The Multilin 339 relay is a member of the 3 Series family of Multilin relays. This motor protective device is used to perform protection, control, metering and supervision of asynchronous LV and MV motors in different process and manufacturing industries.

The basic protection functions of this relay include motor thermal model, time-delayed and instantaneous overcurrent, ground overcurrent and sensitive ground overcurrent protection. Additional control features such as logic control are available for applications that require additional motor control functionality.

The robust 339 streamlines user work flow processes and simplifies engineering tasks such as configuration, wiring, testing, commissioning, and maintenance. This cost-effective relay also offers enhanced features such as diagnostics, preventative maintenance, motor health reports and advanced security features.

Easy to Use

Drawout & Non-Drawout Construction

The 339 is offered in both a drawout or a non-drawout construction. In the drawout case design the 339 simplifies installation and improves site safety as the need to open switchgear doors or rewire the device after testing is eliminated. As communication cables remain connected to the chassis, even when the relay is withdrawn, communications status is retained.

Application Flexibility & Ease of Wiring

Removable terminals ease wiring and in-system testing or troubleshooting.

Available universal CT inputs along with a software-configurable input range (1A and/or 5A) helps to standardize the design and reduce the number of order codes. There is also no need to change the entire relay in case of a design change or future switchgear modifications. Mixed inputs of 1A or 5A are advantageous for applications where the ground CT is different from the phase CTs.

Fast & Simple Configuration

With quick setup screens the 339 requires minimal configuration for standard feeder applications. Utilizing the powerful EnerVista 3 Series setup software, device configuration can be completed in one easy step.

Advanced Communications

Easy Integration Into New or Existing Infrastructure

With several Ethernet and serial port options, and a variety of protocols, the 339 provides advanced and flexible communication selections for new and existing energy management, SCADA and DCS systems.

339 Relay Features

Easy to Configure- 1 Simple Step

Advanced & Flexible Communication Options

Non-drawout case design

Easy to Use - Drawout Case

Diagnostic Alarms

Drawout case design

Enhanced Diagnostics

Preventative Maintenance

The 339 allows users to track relay exposure to extreme environmental conditions by monitoring and alarming at high ambient temperatures. This data allows proactive scheduling of regular maintenance work and upgrade activities. The diagnostics data enables the user to understand degradation of electronics due to extreme conditions.

Switchgear Diagnostics

The current and voltage transformer monitoring feature allows users to easily locate and troubleshoot potential failures or mis-operations caused by CTs or VTs. Trip/Close Circuit Monitoring provides constant monitoring of the health the control circuit.

Failure Alarm

The 339 detects and alarms on communication port and IRIG-B failures. The 339 also enables users to analyze system performance via diagnostics information such as event records, oscillography, etc. It issues detailed motor health reports and alarms when thresholds are exceeded.

Protection & Control

The 339 motor protection system is designed to protect and manage various sizes of LV and MV asynchronous motors motors and driven equipment. Flexible and powerful, the 339 provides advanced motor protection, control and monitoring in one integrated, economical drawout or non-drawout design. The 339 contains a full range of self contained protection and control elements as detailed in the Functional Block Diagram and Features table.

Motor Thermal Model (49, 38, 46, 50L, 66)

To provide optimal protection and maximum runtime, the 339 Motor Protection System employs GE's Industry leading advanced Thermal Model, consisting of six key elements:

- Overload Curves
- Unbalance Biasing
- Hot/Cold Safe Stall Ratio
- Motor Cooling Time Constants
- Thermal Inhibit and Emergency Restart
- RTD Biasing

FlexCurves

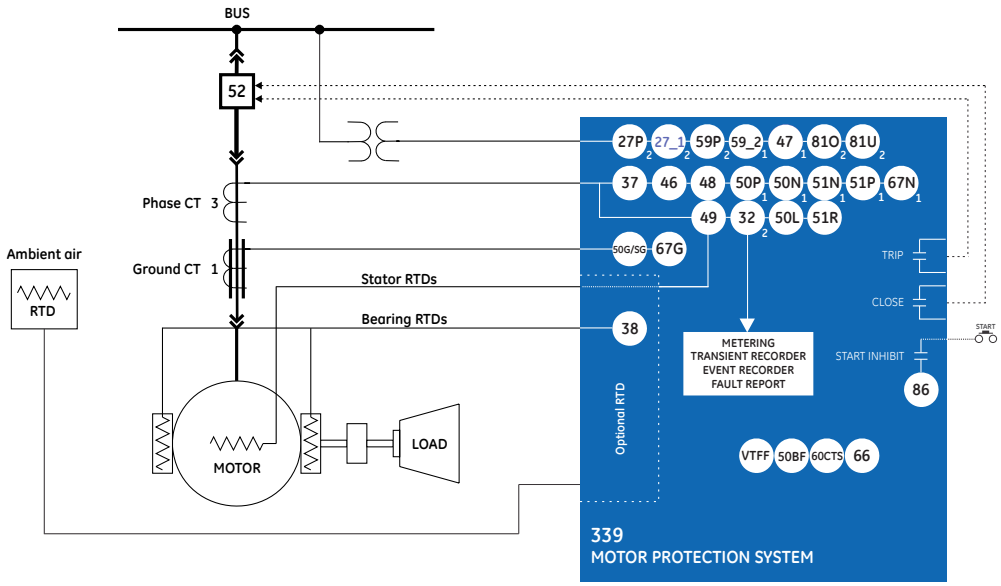
A smooth custom overload curve is created using FlexCurves™. These curves can be used to protect motors with different rotor damage and stator damage curves, allowing total motor design capacity with complete protection.

Voltage and Frequency Protection (27P/_1, 59P/_2, 81O/U)

Overvoltage and Undervoltage elements provide protection for voltage sensitive equipment such as motors as well as control for permissive functions and source transfer schemes.

Overfrequency and underfrequency elements improve network (grid) stability using voltage or frequency based load shedding techniques.

Functional Block Diagram



ANSI® Device Numbers & Functions

DEVICE NUMBER	61850 LOGICAL NODE	DESCRIPTION
27_1	psseqPTUV	Positive Sequence Undervoltage
27P	phsPTUV	Phase Undervoltage
32	PDOP	Directional Power
37	PTUC	Undercurrent
37P	PDUP	Underpower
38	rtdGGIO6	Bearing RTD
		Stator/Ambient/Other
		RTD Trouble Alarm
46	unbalPTOC	Current Unbalance
47	phsrevPTOV	Voltage Phase Reversal
48	accelPTOC	Acceleration Time
49	PTTR	Thermal Protection/Stall Protection
50BF	RBRF	Breaker Failure / Welded Contactor

DEVICE NUMBER	61850 LOGICAL NODE	DESCRIPTION
50G/SG	gndPIOC	Ground Fault/Sensitive Ground Fault (CBCT)
50L	ldincPTOC	Load Increase Alarm
50N	ndPIOC	Neutral Instantaneous Overcurrent
50P	scPIOC	Short Circuit
51N	ndPTOC	Neutral Timed Overcurrent
51P	phsPTOC	Phase Timed Overcurrent
51R	jamPTOC	Mechanical Jam
59_2	ngseqPTOV	Negative Sequence Overvoltage
59P	phsPTOV	Phase Overvoltage
60CTS	-	CT Supervision

DEVICE NUMBER	61850 LOGICAL NODE	DESCRIPTION
66	PMRI	Starts per Hour & Time Between Starts
		Restart Block
		Thermal Inhibit
67G	gndRDIR	Ground Directional Element
67N	ndRDIR	Neutral Directional Element
81O	PTOF	Overfrequency
81U	PTUF	Underfrequency
86	-	Lockout
VTFF (60VTS)	-	VT Fuse Failure

Unbalance (Negative Sequence) Biasing (46)

Negative sequence current, which causes additional rotor heating, is not accounted for in the thermal limit curves provided by the manufacturer. The 339 measures current unbalance as a ratio of negative to positive sequence current. The thermal model is then biased to reflect the additional rotor heating.

RTD Biasing (38)

The Thermal Model relies solely on measured current to determine motor heating, assuming an ambient temperature of 40°C and normal motor cooling. The actual motor temperature will increase due to abnormally high ambient temperatures or if the motor cooling systems have failed.

RTD Biasing enhances the motor thermal model by calculating the thermal capacity used based on available Stator RTD temperatures.

RTD Biasing does not replace the Thermal Capacity Used (TCU) calculated using the motor current. It provides a second and independent measure of thermal capacity used. Based on a programmable curve, the 339 will calculate the TCU at any given temperature. This TCU is then compared to that of the thermal model, and the larger of the two will be used.

Hot / Cold Safe Stall Ratio

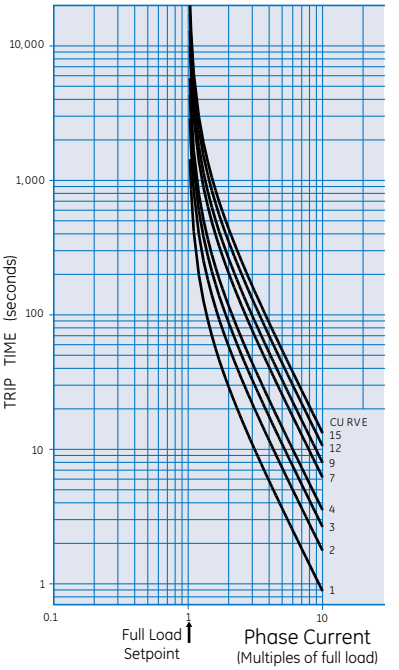
The ratio defines the steady state level of thermal capacity used (TCU) by the motor. This level corresponds to normal operating temperature of a fully loaded motor and will be adjusted proportionally if the motor load is lower than rated.

Motor Cool Time Constants

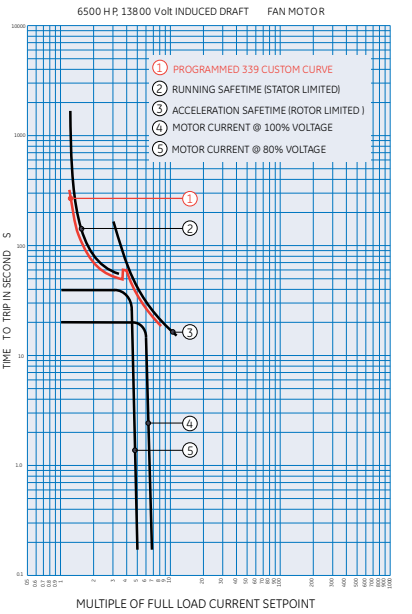
The 339 has a true exponential cooldown characteristic which mimics actual motor cooling rates, providing that motor cooling time constants are available for both the stopped and running states. When ordered with RTD's the stopped and running cool time constants will be calculated by the 339 based on the cooling rate of the hottest RTD, the hot/cold stall ratio, the ambient temperature, the measured motor load and the programmed service factor or overload pickup.

Start Inhibit

The Start Inhibit function prevents starting of a motor when insufficient thermal capacity is available or a motor start supervision function dictates inhibit.



15 Standard Curves available in the 339.



Typical Flexcurve

Motor Start Supervision (66)

Motor Start Supervision consists of the following features: Time-Between-Starts, Starts-per-hour, Restart Time.

These elements guard the motor against excessive starting duty, which is normally defined by the motor manufacturer in addition to the thermal damage curves.

Undercurrent/Underpower (37)

The undercurrent function is used to detect a decrease in motor current caused by a decrease in motor load. This is especially useful for indication of conditions such as: loss of suction for pumps, loss of airflow for fans, or a broken belt for conveyors. A separate undercurrent alarm may be set to provide early warning.

Directional Power (32)

The Directional Power element responds to three-phase directional power and is designed for reverse power (32REV) and low forward power (32FWD). One of the applications is to prevent motors running like generators when the motor supplies active power.

Mechanical Jam (51R)

During overload conditions, quick motor shutdown can reduce damage to gears, bearings and other mechanical parts associated with the drive combination.

Ground Overcurrent (50N, 50G/SG, 51N)

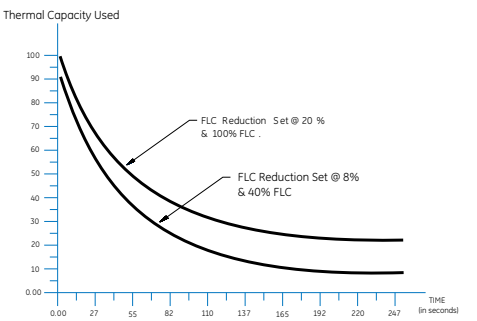
For zero sequence ground overcurrent protection, all three of the motor conductors must pass through a separate ground CT. CTs may be selected to detect either high-impedance zero sequence ground or residual ground currents. The ground fault trip can be instantaneous or programmed for a time delay.

Directional Overcurrent (67N, 67G)

The Neutral Directional element is used to discriminate between faults that occur in the forward direction, and faults that occur in the reverse direction.

RTD Protection (38)

The 339 provides programmable RTD inputs via the remote RMIO that are used for monitoring



Motor cooling curves

the Stator, Bearing and Ambient temperatures. Each RTD input has 2 operational levels: alarm and trip. The 339 supports RTD trip voting and provides open and short RTD monitoring.

CIO has been designed to be mounted close to the motor to reduce the length of the RTD cables and the associated costs. It can be mounted UP TO 250m away from the relay.

Contactor Current Supervision

The fault current can exceed the withstand current which contactor is rated to interrupt. The 339 blocks the operation of the output trip relay and operates a selected auxiliary output relay to transfer the trip to the upstream breaker which is rated to interrupt the fault currents.

VFD-Driven Motor Protection

The Multilin 339 provides protection and control for motors fed through VFDs (Variable Frequency Drives). An advanced algorithm allows switchable current and voltage tracking in case VFD is bypassed.

Two-speed motor

Two-speed motors have two windings wound into one stator. These motors rely on contactors to accomplish speed changes by altering the winding configurations. The 339 motor relay provides a complete set of protective functions for each speed.

Automation and Integration

Logic Elements

The 339 relay has sixteen Logic Elements available for the user to build simple logic using the state of any programmed contact, virtual, or remote input, or the output operand of a protection or control element.

Use the logic element feature to assign up to eight triggering inputs in an "AND/OR/NOR/NAND/XOR/XNOR" gate for the logic element operation, and up to four blocking inputs in an "AND/OR/NOR/NAND/XOR/XNOR" gate for defining the block signal. Pickup and dropout timers are available for delaying the operation and reset.

Inputs/Outputs

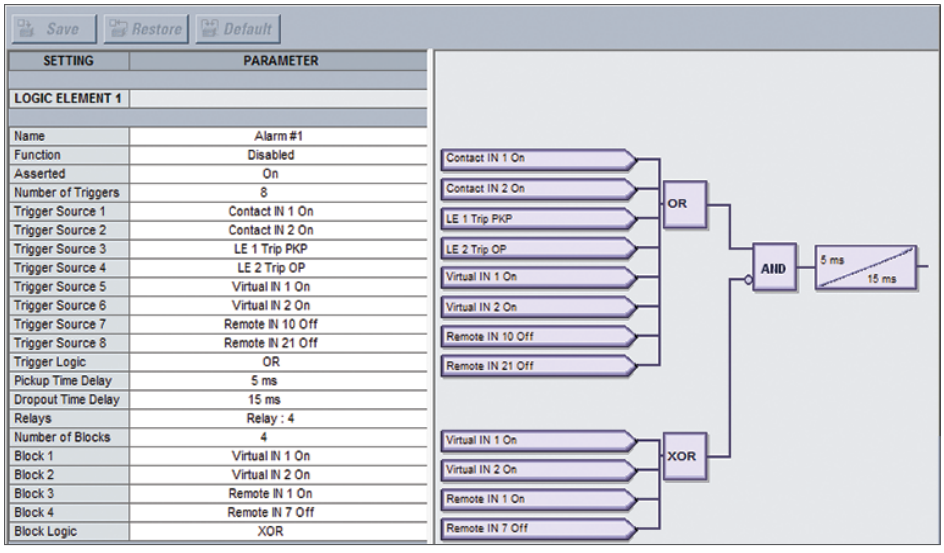
The 339 features the following inputs and outputs for monitoring and control of typical motor applications:

- 10 contact Inputs with programmable thresholds
- 7 Outputs (2 Form A, 5 Form C) as standard and 4 Outputs (1 Form A, 3 Form C) when internal RTD option is selected
- 5 Form C output relays

Virtual Inputs

Virtual inputs allow communication devices the ability to write digital commands to the 339 relay. These commands could be starting or stopping the motor or blocking protection elements.

Logic Designer



Sixteen logic elements available for applications such as manual control, interlocking and peer to peer tripping.

Breaker Failure/Welded Contactor (50BF)

The Breaker Failure function is used to determine when a trip command sent to a breaker has not been executed within a selectable time delay. In the event of a breaker failure, the 339 will issue an additional signal to trip the breakers connected to the same busbar or to signal the trip of upstream breakers.

IEC 61850

The 339 supports IEC 61850 Logical Nodes which allows for digital communications to DCS, SCADA and higher level control systems.

In addition, the 339 also supports IEC 61850 GOOSE communication, providing a means of sharing digital point state information between 339's or other IEC 61850 compliant IED's.

- Eliminates the need for hardwiring contact inputs to contact outputs via communication messaging.
- Transmits information from one relay to the next in as fast as 8 ms.
- Enables sequence coordination with upstream and downstream devices.
- When Breaker Open operation malfunctions, GOOSE messaging sends a signal to the upstream breaker to trip and clear the fault.

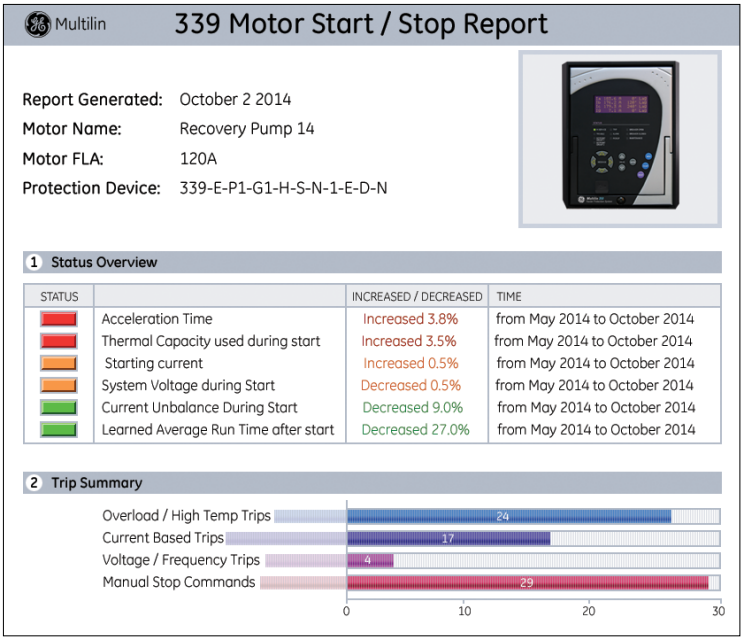
Metering, Monitoring and Diagnostics

Event Recording

Events consist of a broad range of change of state occurrences, including pickups, trips, contact operations, alarms and self test status. The 339 relay stores up to 256 events, time tagged to the nearest millisecond. This provides the information required to determine sequence of events, facilitating the diagnosis of relay operation. Event types are individually maskable in order to avoid generating undesired events, and include the metered values at the moment of the event.

Oscillography/ Transient Fault Recorder

The 339 captures current and voltage waveforms and digital channels at up to 32 samples per cycle (user-selectable). Multiple records can be stored in the relay at any given time with a maximum length of 192 cycles Oscillography is triggered either by internal signals or an external contact.



The Motor Heath Report allows you to easily "see" how your motor is doing:

- *Start/stop history*
- *Comprehensive trip details*
- *Learned acceleration time and starting current*
- *Many other motor health details*

Test Mode

The Test Mode for 3 Series relays consists of testing front panel LEDs, Inputs and Outputs. It can be used to test the SCADA system as well.

Statistical Data

The 339 records the following statistical data in order to assist in diagnosing common motor faults, as well as assisting in planning preventative maintenance.

- Total running hours
- Number of motor starts
- Total number of motor trips

Trip/Close Coil Monitoring

The 339 can be used to monitor the integrity of both the breaker trip and closing coils and circuits. The supervision inputs monitor both the auxiliary voltage levels, while the outputs monitor the continuity of the trip and/or closing circuits, by applying a small current through the circuits.

Pre-Trip Alarms

The 339 can trigger an alarm prior to a trip caused by the following conditions:

- Thermal Overload
- Ground Fault
- Unbalance
- Undercurrent
- RTD over temperature
- Broken RTD sensor
- Internal self-test

Metering Actual Values

The 339 provides users with the following metering information in order to accurately monitor the operating conditions of the motor:

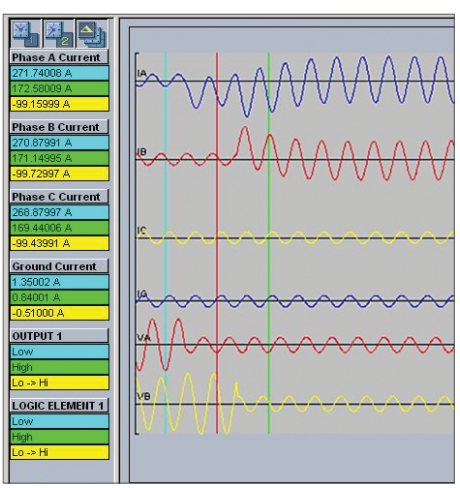
- Current: Ia, Ib, Ic, In, Ig, Isg
- Phase-to-phase and phase-to-ground voltages: Van, Vbn, Vcn, Vab, Vbc, Vca
- Active power (3-phase) kW
- Reactive power (3-phase) kVAR
- Frequency
- Current Unbalance
- Motor load current as a % of full load
- Motor thermal capacity used
- Stator/Bearing/Ambient RTD temperature
- Demand (different types)

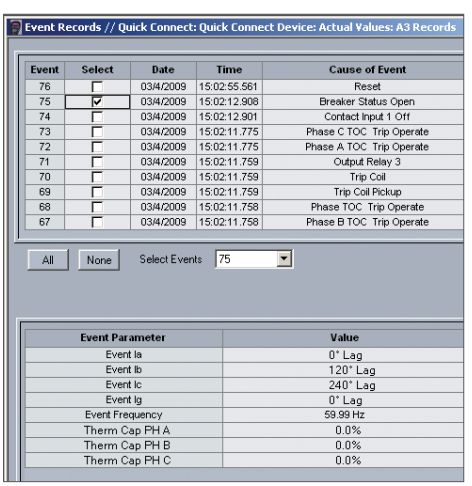
Advanced Device Health Diagnostics

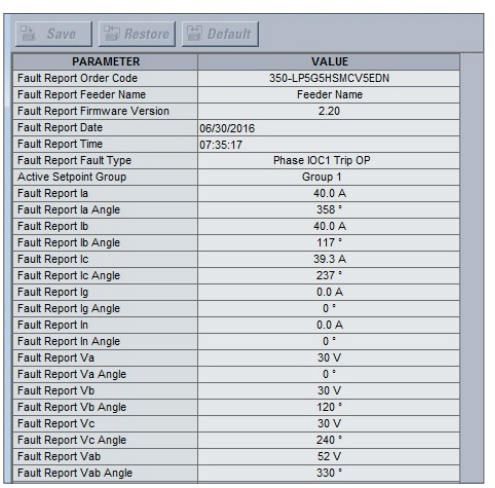
The 339 performs comprehensive device health diagnostic tests during startup and continuously at runtime to test major functions and critical hardware. These diagnostic tests monitor for conditions that could impact system reliability. Device status is communicated via SCADA

Power System Troubleshooting

Analyze power system disturbances with transient fault recorder and event records







SECURITY/CHANGE HISTORY REPORT

Generated at: September 15 2010 16:56:05

Device Summary

Device Name:	339
Device Type:	SR 339
Order Code:	339-CP5G5HESNP2EDH
Firmware Version:	1.30
Serial Number:	BL0A09000564
Communication:	COM 3, 115200

Setting Changes History

Session#	Date of Change	Method of Change	# Of Changes	Password Entered	Changes by Whom IP /Mac	Event Type	Filename	Status	Firm. Version
1	09/15/2010 07:09:05 PM	USB	25	Yes	0:0:0:0	Setpoint Change		Relay Not Ready	130
2	09/15/2010 07:13:32 PM	USB	2	Yes	3:13:81:141	Setpoint Change		Relay Ready	130

Setting Changes Detail History

Session#	Date Of Change	Old Value	New Value	Data Item	Modbus Address
1	09/15/2010 07:09:05 PM	0	1	Relay Status	0X39e
1	09/15/2010 07:09:13 PM	120	240	Bus VT Secondary	0X118
1	09/15/2010 07:09:20 PM	0	1	Supply Frequency	0X11b
1	09/15/2010 07:09:35 PM	100	1500	CT Primary	0X10a
1	09/15/2010 07:09:48 PM	0	448	Low Speed Switch	0X57e
1	09/15/2010 07:09:53 PM	0	1	Enable Two Speed Motor	0X136
1	09/15/2010 07:10:07 PM	0	1	Thermal Overload Function	0X2b9
1	09/15/2010 07:10:07 PM	0	1	Thermal Alarm Function	0X2bc
1	09/15/2010 07:10:18 PM	0	1	Short Circuit Function	0X3b3
1	09/15/2010 07:10:36 PM	0	1	Mechanical Jam Function	0X2cd

GE Multilin EnerVista VIEWPOINT maintenance

Trace any setting changes with security audit trail

communications and the front panel display. This continuous monitoring and early detection of possible issues helps improve system availability by employing predictive maintenance.

Time Synchronization

IRIG-B is a standard time code format that allows time stamping of events to be synchronized among connected devices to within 1 millisecond. An IRIG-B input is provided in the 339 to allow time synchronization using a GPS clock over a wide area. The 339 IRIG-B supports both AM and DC time synchronization, with an auto detect feature that that eliminates the need for configuration.

Temperature Monitoring

The 339 continually monitors ambient temperature around the relay and alarms when the device is exposed to extreme temperatures and undesirable conditions such as airconditioning unit or station heater failures.

The EnerVista Viewpoint maintenance tool allows users to review and analyze the time period a 339 relay is exposed to certain temperature ranges.

Motor Health Report

The Multilin 339 relay provides motor diagnostic information in a legible easy to use format that enables the user to make informed decisions on the health of their motor.

Based on the graphical representation and trended values of the motor data gathered by the 339, this enables users to quickly identify process and motor issues prior to a process failure.

The 339 Motor Health Report provides a summary page detailing information on related motor performance.

The following information is detailed in the 339 Motor Health Report:

- Motor Acceleration Time
- Starting Current
- Thermal capacity used during starting
- Average Motor Load
- Average Phase currents
- Current unbalance
- Ground current

Security

Password Control

The password system has been designed to facilitate a hierarchy for centralized management. With the implementation of the Password Security feature in the 339 relay, extra measures have been taken to ensure unauthorized changes are not made to the relay. When password security is enabled, changing of setpoints or issuing of commands requires passwords to be entered. Separate passwords are supported for remote and local operators, and separate access levels support changing of setpoints or sending commands.

Advanced Communications

The 339 utilizes the most advanced communication technologies today making it the easiest and most flexible motor protection relay to use and integrate into new and existing infrastructures. Multiple communication ports and protocols allow control and easy access to information from the 339. All communication ports are capable of communicating simultaneously.

The 339 supports the most popular industry standard protocols enabling easy, direct integration into electrical SCADA and HMI systems. Modbus RTU is provided as standard with a RS485 networking port. The following optional protocols are available:

- IEC 61850
- IEC 61850 GOOSE
- DNP 3.0
- Modbus RTU
- Modbus TCP/IP
- IEC 60870-5-104
- IEC 60870-5-103

EnerVista Software

The EnerVista™ suite is an industry leading set of software programs that simplifies every aspect of using the 339 relay. The EnerVista suite provides all the tools to monitor the status of the protected asset, maintain the relay, and integrate the information measured into DCS or SCADA monitoring systems. Convenient COMTRADE and sequence of event viewers are an integral part of the 339 set up software and are included to ensure proper protection and system operation.

Simplified Motor Setting

Included with every 339 Motor Protection System is the Multilin Simplified Motor Setup. The Simplified Motor Setup provides users with a quick and easy method to setup and start the motor and process in applications that require fast commissioning.

The Simplified Motor Setup will generate a complete 339 setting file based on the motor nameplate and system information entered by the user. Once all the information is entered, the Simplified Motor Setup will generate the settings file, as well as provide the documentation indicating which settings were enabled, along with an explanation of the specific parameters entered. The Simplified Motor Setup will provide a detailed setting file in PDF format that can be saved or printed for future reference.

Launchpad

EnerVista Launchpad is a powerful software package that provides users with all of the set up and support tools needed for configuring and maintaining GE products. The setup software within Launchpad allows configuring devices in real time by communicating using serial, Ethernet or modem connections, or offline by creating setting files to be sent to devices at a later time.

Included in Launchpad is a document archiving and management system that ensures critical documentation is up-to-date and available when needed. Documents made available include:

- Manuals
- Application Notes
- Guideform Specifications
- Brochures
- Wiring Diagrams
- FAQs
- SService Bulletins

Viewpoint Monitoring

Viewpoint Monitoring is a simple to use and full featured monitoring and data recording software package for small systems. Viewpoint monitoring provides a complete HMI package with the following functionality:

- Plug and play device monitoring
- System single line monitoring and control
- Annunciator alarm screens
- Trending reports
- Automatic event retrieval
- Automatic waveform retrieval

Viewpoint Maintenance

Viewpoint Maintenance provides tools that will increase the security of the 339 Motor Protection System. Viewpoint Maintenance will create reports on the operating status of the relay, and simplify the steps to troubleshoot protected motors.

The tools available in Viewpoint Maintenance include:

- Settings Security Audit Trail
- Device Health Report
- Comprehensive Fault Diagnostics

EnerVista Integrator

EnerVista Integrator is a toolkit that allows seamless integration of Multilin devices into new or existing automation systems.

Included in the EnerVista Integrator is:

- OPC/DDE Server
- Multilin Devices
- Automatic Event Retrieval
- Automatic Waveform Retrievel

User Interface

TWELVE LEDS *(8 optional programmable LEDs)*

IN SERVICE: *This indicator will be on continuously lit if the relay is functioning normally and no major self-test errors have been detected.*

TROUBLE: *Trouble indicator LED will be AMBER if there is a problem with the relay or if relay is not programmed.*

LOCKOUT: *Lockout initiates when a lockout trip is active.*

RUNNING: Indicates that the motor is running in normal operation

STOPPED: *Indicates that the motor is stopped*

STARTING: *Indicates that the motor is in the starting process*

TRIP: *Indicates that the relay has tripped the motor offline based on predefined programmed conditions.*

ALARM: *Indicates that the motor is currently operating in an alarm condition and may proceed to a trip condition if not addressed.*

MAINTENANCE: *Environmental alarms such as ambient temperature alarm, coil monitor or trip counter.*

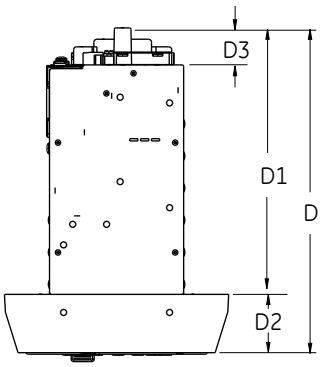
The display messages are organized into Main Menus, Pages, and Sub-pages.

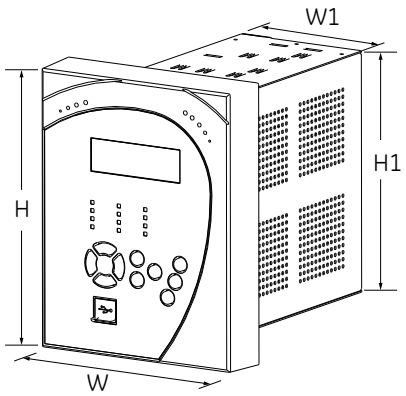
There are four main menus labeled Actual Values, Quick Setup, Setpoints, and Maintenance. Pressing the MENU key followed by the MESSAGE key scrolls through the four Main Menu Headers.
The ten button keypad allows users easy access to relay configuration information and control commands.

INSTALLATION OPTIONS:

Draw out and non draw out options available

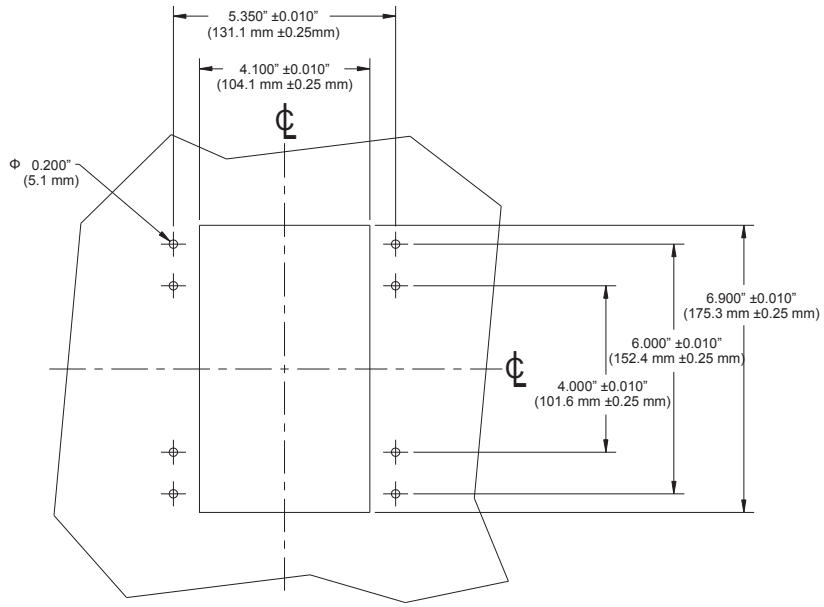
Dimensions



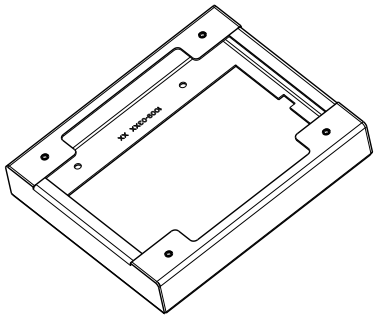


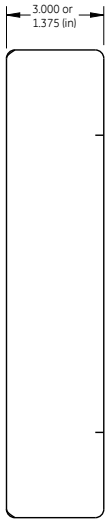
	DRAWOUT		NON-DRAWOUT	
	in	mm	in	mm
H	7.93	201.5	7.98	202.7
W	6.62	168.2	6.23	158.2
D	9.62	244.2	9.35	237.5
W1	3.96	100.6	3.96	100.6
D1	7.89	200.4	7.88	200.2
D2	1.73	43.8	1.47	37.3
D3	1.087	27.6	0.755	19.17
H1	6.82	173.2	6.82	173.2

Mounting

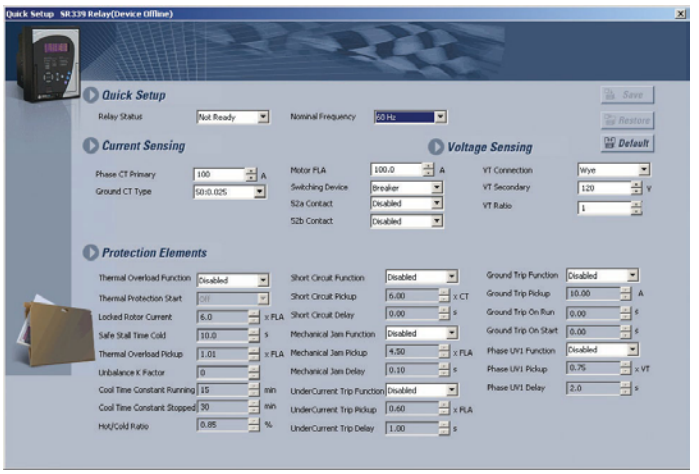


3 Series Depth Reducing Collar

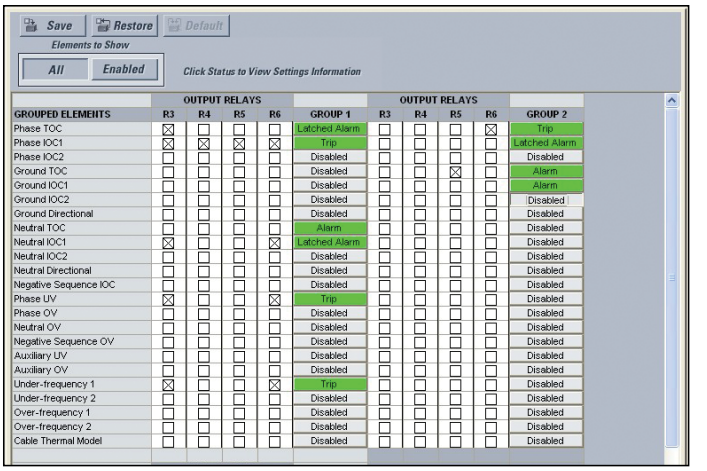




Feeder protection settings in one easy step



Fast and accurate configuration in one simple screen.



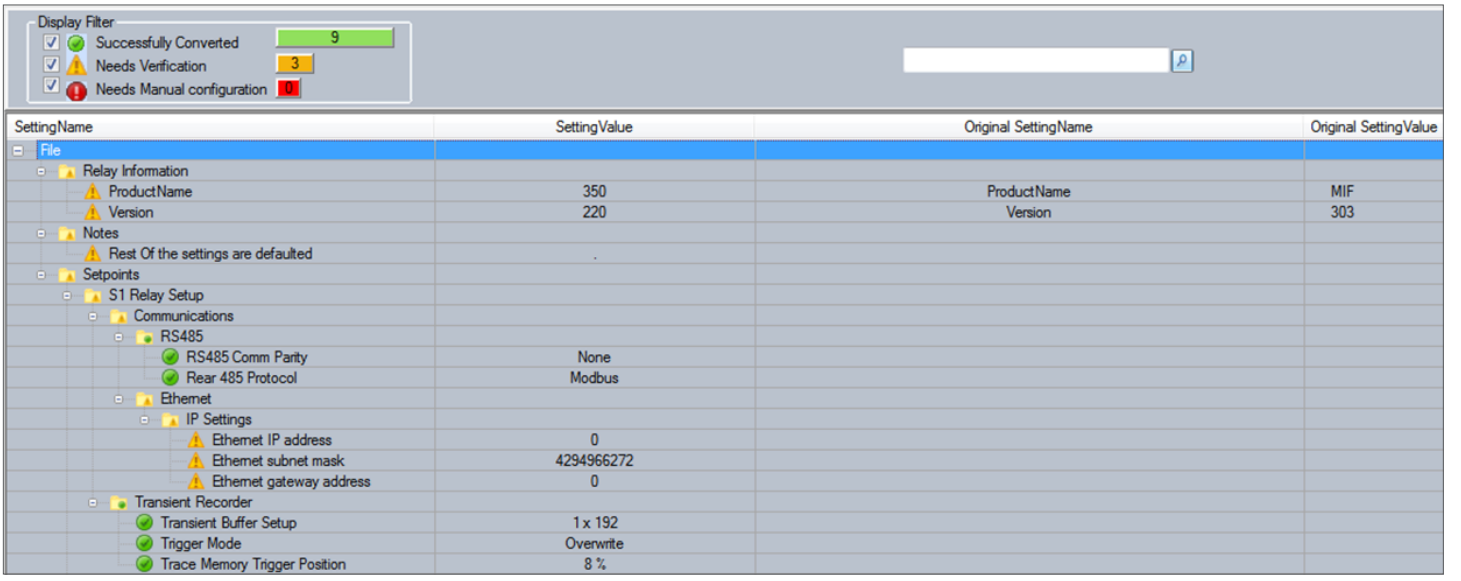
3 Series setup software protection summary for viewing a summary of Protection & Control configuration.

Retrofit Existing Multilin MII Family Devices

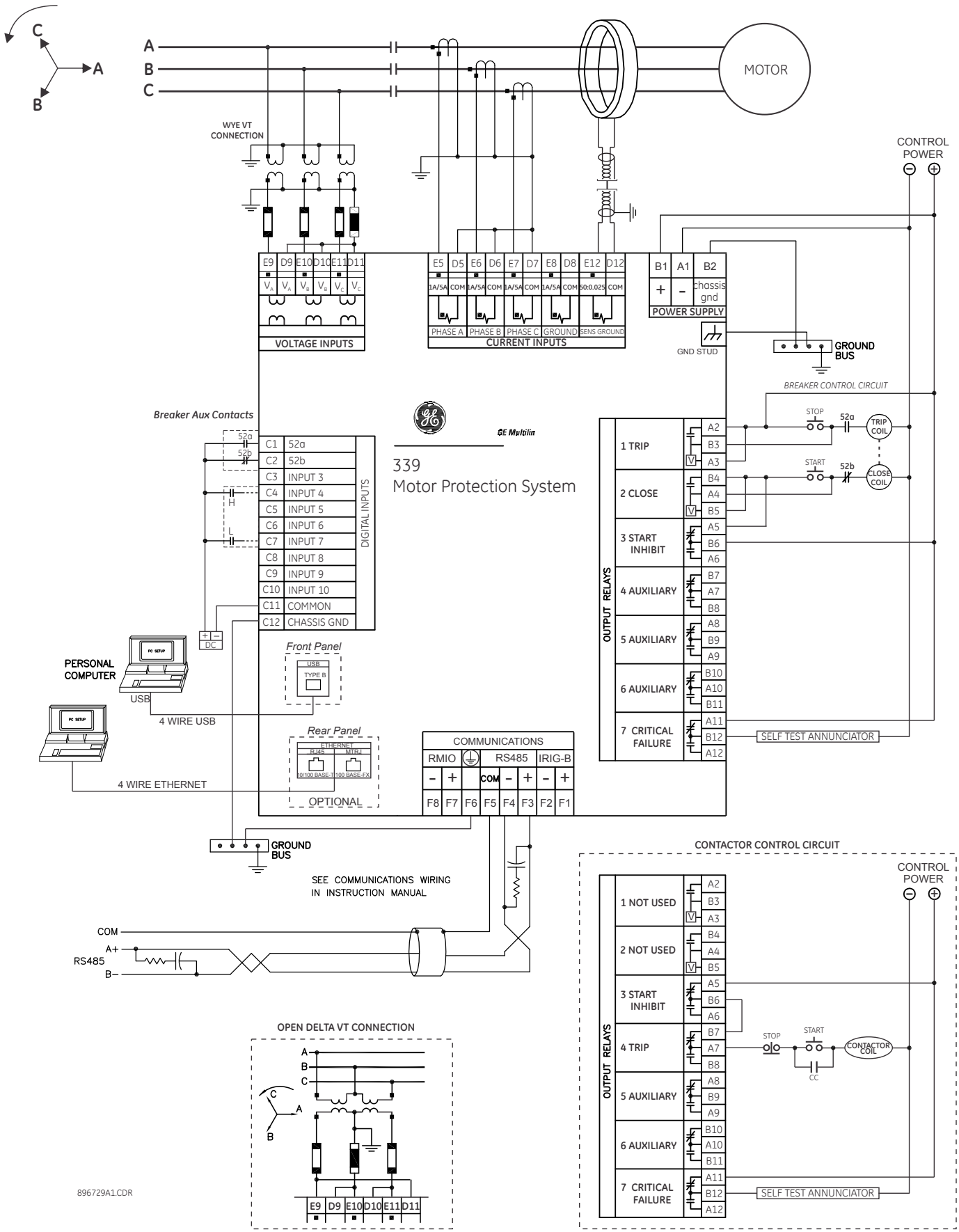
Traditionally, retrofitting or upgrading an existing relay has been a challenging and time consuming task often requiring re-engineering, panel modifications and re-wiring. Similar features and form factor of some models of MII family devices allow users to replace their existing relays with 3 Series relays with enhanced protection and control features and advanced communications.

The SR3 Enervista Setup software allows users to create new setting files based on existing MIFII and MIVII setting files and can be uploaded to a 339 relay with a compatible model number. Retrofit is smooth and simplified with minor wiring or switchgear modifications.

1. Find the **Equivalent Model Number**
2. Update **Settings File**
3. Replace **Relay**
4. **Re-wire**



Wiring Diagram



Technical Specifications

PASSWORD SECURITY	
Master Reset Password:	8 to 10 alpha-numeric characters
Settings Password:	3 to 10 alpha-numeric characters for local or remote access
Control Password:	3 to 10 alpha-numeric characters for local or remote access

NEUTRAL INSTANTANEOUS OVERCURRENT (50N)	
Pickup Level:	0.05 to 20 x CT in steps of 0.01 x CT
Dropout Level:	96 to 99% of Pickup @ I > 1 x CT Pickup - 0.02 x CT @ I <1 x CT
Time Delay:	0.00 to 300.00 sec in steps of 0.01
Operate Time:	<30 ms @ 60Hz (I > 2.0 x PKP), 0 ms time delay <35 ms @ 50Hz (I > 2.0 x PKP), 0 ms time delay
Timer Accuracy:	0 to 1 cycle
Level Accuracy:	per CT input
Elements:	Trip or Alarm

NEUTRAL DIRECTIONAL OVERCURRENT (67N)	
Directionality:	Co-existing forward and reverse
Polarizing:	Voltage, Current, Dual
Polarizing Voltage:	$-V_0$ calculated using phase voltages (VTs must be connected in "Wye")
Polarizing Current:	I_G
MTA:	From 0° to 359° in steps of 1°
Angle Accuracy:	4
Operation Delay:	20 to 30 ms

PHASE/NEUTRAL TIMED OVERCURRENT (51P/51N)	
Pickup Leve:	0.05 to 20.00 x CT in steps of 0.01 x CT
Dropout Level:	97 to 99% of Pickup @ I > 1 x CT
Pickup	0.02 x CT @ I < 1 x CT
Curve Shape:	ANSI Extremely/Very/Moderately/ Normally Inverse Definite Time (0.1 s base curve) IEC Curve A/B/C and Short Inverse IAC Extremely/Very/-/Short Inverse
Curve Multiplier:	0.05 to 20.00 in steps of 0.01
Reset Time:	Instantaneous, Linear
Curve Timing Accuracy:	±3% of expected inverse time or 1 cycle, whichever is greater, from pickup to operate
Level Accuracy:	per CT input

DIRECTIONAL POWER (32)	
Measured power:	3-phase
Characteristic angle:	0° to 359° in steps of 1°
Power pickup range:	-1.200 to 1.200 x Rated Power in steps of 0.001
Pickup level accuracy:	± 1% or ± 0.001 x Rated Power, whichever is greater
Hysteresis:	2% or 0.001 x Rated Power, whichever is greater
Pickup time delay:	0.00 to 600 .0 s in steps of 0.1 s
Operate time:	< 55 ms at 1.1 x pickup at 60 Hz < 65 ms at 1.1 x pickup at 50 Hz
Timer accuracy:	± 3% of delay setting or ± ¼ cycle (whichever is greater) from pickup to operate

UNDERCURRENT (37)	
Pickup Level:	0.1 to 0.95 x FLA in steps of 0.01 x FLA
Dropout Level:	101 to 104% of Pickup
Time Delay:	1.00 to 60.00 s in steps of 0.01 s
Block from Start:	0 to 600 s in steps of 1 s
Pickup Accuracy:	as per phase current inputs
Timing Accuracy:	±0.5 s or ± 0.5% of total time
Level Accuracy:	per CT input
Elements:	Trip or Alarm

CURRENT UNBALANCE (46)	
Unbalance Pickup Level:	4.00 to 40.00% in steps of 0.01%
Trip Curves:	Definite time, Inverse time
Trip TDM:	1.00 to 100.00 s in steps of 0.01 s
Trip Maximum Time:	1.00 to 1000.00 s in steps of 0.01 s
Trip Minimum Time:	1.00 to 1000.00 s in steps of 0.01 s
Trip Reset Time:	1.00 to 1000.00 s in steps of 0.01 s
Alarm Time Delay:.	1.00 to 60.00 s in steps of 0.01 s
Single Phasing Pickup Level:	unbalance level > 40% or when Iavg ≥25%FLA and current in any phase is less than the cutoff current
Single Phasing Time Delay:	2 sec
Dropout Level:	96 to 99% of pickup
Pickup Accuracy:	±2%
Timing Accuracy:	±0.5 s or ± 0.5% of total time
Unbalance Elements:	Trip and Alarm
Single Phasing Elements:	Trip

RTD (38)	
Pickup:	1 to 250°C in steps of 1°C
Pickup Hysteresis:	2°C
Time Delay:	3 sec
Elements:	Trip and Alarm

RTD TROUBLE ALARM (38)	
RTD Trouble Alarm:	<-50°C or >250°C

LOAD INCREASE ALARM	
Pickup Level:	50 to 150%FLA in steps of 1%FLA
Dropout Level:	96 to 99% of Pickup
Alarm Time Delay:	1.00 to 60.00 s in steps of 0.01 s
Pickup Accuracy:	as per phase current inputs
Timing Accuracy:	±0.5 s or ±0.5% of total time

SHORT CIRCUIT	
Pickup Level:	1.00 to 20.00 x CT in steps of 0.01 x CT
Dropout Level:	96 to 99% of Pickup @ I > 1 x CT Pickup - 0.02 x CT @ I < 1 x CT
Alarm Time Delay:	0.00 to 60.00 s in steps of 0.01 s
Pickup Accuracy:	as per phase current inputs
Operate Time:	<30 ms @ 60Hz (I > 2.0 x PKP), 0 ms time delay <35 ms @ 50Hz (I > 2.0 x PKP), 0 ms time delay
Timing Accuracy:	0 to 1 cycle
Elements:	Trip or Alarm

MECHANICAL JAM TRIP (51R)	
Pickup Level:	1.01 to 4.50 x FLA in steps of 0.01 x FLA, blocked from start
Dropout Level:	96 to 99% of Pickup
Trip Time Delay:	0.10 to 30.00 s in steps of 0.01 s
Pickup Accuracy:	as per phase current inputs
Timing Accuracy:	±0.5 s or ±0.5% of total time

GROUND FAULT/SENSITIVE GROUND FAULT (CBCT) (50G/SG)	
Pickup Level:	0.03 to 1.00 x CT in steps of 0.01 x CT 0.50 to 15.00 A in steps of 0.01 A (CBCT)
Dropout Level:	Pickup - 0.02 x CT 96 to 99% of Pickup (CBCT)
Alarm Time Delay on Run:	0.00 to 60.00 s in steps of 0.01 s
Alarm Time Delay on Start:	0.00 to 60.00 s in steps of 0.01 s
Trip Time Delay on Run:	0.00 to 5.00 s in steps of 0.01 s
Trip Time Delay on Start:	0.00 to 10.00 s in steps of 0.01 s
Pickup Accuracy:	as per ground current inputs
Operate Time:	<30 ms @ 60Hz (I > 2.0 x PKP), 0 ms time delay <35 ms @ 50Hz (I > 2.0 x PKP), 0 ms time delay
Timing Accuracy:	0 to 1 cycle
Elements:	Trip and Alarm

UNDERPOWER (37)	
Pickup Level:	1 to 100% Hz MNR 1%
Dropout Level:	101% to 104% of Pickup
Time Delay:	1.0 to 60.0 s in steps of 0.1
Pickup Accuracy:	as per power monitoring specification
Timing Accuracy:	±0.5 s or ±0.5% of total time
Elements:	Trip and Alarm

THERMAL PROTECTION (49)	
Locked Rotor Current:	2.0 to 11.0 x FLA in steps of 0.1 x FLA
Safe Stall Time:	1.0 to 600.0 s in steps of 0.1 s
Curve Multiplier:	1 to 15 in steps of 1
Pickup Level:	1.01 to 1.25 x FLA in steps of 0.01 x FLA
Curve Biasing:	Phase unbalance Hot/cold biasing Stator RTD biasing Exponential Running and Stopped Cooling Rates
TCU Update Rate:	3 cycles
Pickup Accuracy:	per phase current inputs
Timing Accuracy:	± 200 ms or ±2% of total time
Elements:	Trip and Alarm

PHASE/AUXILIARY UNDERVOLTAGE (27P/27X)	
Minimum Voltage:	Programmable from 0.00 to 1.25 x VT in steps of 0.01
Pickup Level:	0.00 to 1.25 x VT in steps of 0.01
Dropout Level:	101 to 104% of pickup
Curve:	Definite Time, Inverse Time
Time Delay:	0.1 to 600.0 s in steps of 0.1
Operate Time:	Time delay ±30 ms @ 60 Hz (V < 0.85 x PKP) Time delay ±40 ms @ 50 Hz (V < 0.85 x PKP)
Time Delay Accuracy:	±3% of expected time, or 1 cycle, whichever is greater
Level Accuracy:	Per voltage input

NEGATIVE SEQUENCE/PHASE OVERVOLTAGE (59P/59_2)	
Pickup Level:	0.00 to 1.25 x VT in steps of 0.01
Dropout Level:	96 to 99% of pickup
Time Delay:	0.1 to 600.0 s in steps of 0.1
Operate Time:	Time delay ±30 ms @ 60 Hz (V < 0.85 x PKP) Time delay ±40 ms @ 50 Hz (V > 1.1 x PKP)
Timing Accuracy:	±0.5 s or ±0.3% of total time
Level Accuracy:	Per voltage input

PHASE REVERSAL (47)	
Configuration:	ABC or ACB phase rotation
Time Delay:	100 ms
Timing Accuracy:	±0.5 s
Elements:	Trip or Alarm

UNDERFREQUENCY (81U)	
Minimum Voltage:	0.00 to 1.25 x VT in steps of 0.01
Pickup Level:	40.00 to 70.00 Hz in steps of 0.01
Dropout Level:	Pickup +0.05 Hz
Time Delay:	0.1 to 600.0 s in steps of 0.1
Timing Accuracy:	±0.5 s or ±0.5% of total time
Level Accuracy:	±0.03 Hz
Elements	Trip and Alarm

OVERFREQUENCY (81O)	
Minimum Voltage:	0.3xVT
Pickup Level:	40.00 to 70.00 Hz in steps of 0.01
Dropout Level:	Pickup -0.05 Hz
Time Delay:	0.1 to 600.0 s in steps of 0.1
Timing Accuracy:	±0.5 s or ±0.5% of total time
Level Accuracy:	±0.03 Hz
Elements	Trip and Alarm

ACCELERATION TIME TRIP (48)	
Pickup Level:	Motor start condition
Dropout Level:	Motor run, trip, or stop condition
Timers for single-speed:	Stopped to running
Timers for two-speed:	Stopped to high speed, stopped to low speed, low to high speed
Time Delay:	1.0 to 250.0 s in steps of 0.1
Timing Accuracy:	±200 ms or ±1% of total time

MOTOR START DATA LOGGER	
Length:	6 buffers, containing a total of 30 seconds of motor starting data
Trigger:	Motor start status
Trigger Position:	1-second pre-trigger duration
Logging Rate:	1 sample/200 ms

FUSE FAIL (VTFF)	
Time Delay:	1 s
Timing Accuracy:	±0.5 s
Elements	Trip or Alarm

FAULT RECORDER	
Number of records:	1
Content:	Date and Time, first cause of fault, phases
Current:	Ia, Ib, Ib, Ig/Isg, In - magnitudes and angles
Voltages:	Van, Vbn, Vcn, Vab, Vbc, Vca, Vaux - magnitudes and angles
System frequency	

TRANSIENT RECORDER	
Buffer size:	3 s
No. of buffers:	1x192, 3x64, 6x32
No. of channels:	14
Sampling rate:	32 samples per cycle
Triggers:	Manual Command Contact Input Virtual Input Logic Element Element Pickup/Trip/Dropout/Alarm
Data:	AC input channels Contact input state Contact output state Virtual input state Logic element state
Data storage:	RAM - battery backed-up

EVENT RECORDER	
Number of events:	256
Content:	event number, date of event, cause of event, per-phase current, ground current, sensitive ground current, neutral current, per-phase voltage (VTs connected in "Wye"), or phase-phase voltages (VTs connected in "Delta"), system frequency, power, power factor, thermal capacity, motor load, current unbalance
Data Storage:	Non-volatile memory

LEARNED DATA RECORDER	
Number of events:	250
Header:	Date, number of records
Content:	learned acceleration time , learned starting current, learned starting capacity, last starting current, last starting capacity, last acceleration time , average motor load learned, average run time after start (days), average run time after start (minutes)
Data Storage:	Non-volatile memory

Technical Specifications

CLOCK	
Setup:	Date and time Daylight Saving Time RTC Accuracy: ± 1 min / month at 25°C
IRIG-B:	Auto-detect (DC shift or Amplitude Modulated) Amplitude modulated: 1 to 10 V pk-pk DC shift: 1 to 10 V DC Input impedance: 40 kOhm ± 10%
Accuracy with IRIG-B:	± 1 ms
Accuracy without IRIG-B:	± 1 minute/month

LOGIC ELEMENTS	
Number of logic elements:	16
Trigger source inputs per element:	2 to 8
Block inputs per element:	2 to 4
Supported operations:	AND, OR, NOR, NAND, XOR, XNOR, Pickup / Dropout timers
Pickup timer:	0 to 60000 ms in steps of 1 ms
Dropout timer:	0 to 60000 ms in steps of 1 ms

BREAKER CONTROL	
Operation:	Asserted Contact Input, Logic Element, Virtual Input, Manual Command, Remote Input
Function:	Opens/closes the motor breaker

START INHIBIT	
Thermal Start Inhibit:	Thermal Inhibit Margin: 0 to 25 % in steps of 1%
Starts per Hour Inhibit:	Maximum: 1 to 5 starts in steps of 1
Time Between Starts Inhibit:	Time Between Starts: 1 to 3600 s in steps of 1 s
Restart Inhibit:	Restart Inhibit Delay: 1 to 50000 s in steps of 1 s

BREAKER FAILURE/WELDED CONTACTOR	
Current Supervision:	Phase Current
Current Supervision Pickup:	0.05 to 20.00 x CT in steps of 0.01 x CT
Time Delay 1:	0.03 to 1.00 s in steps of 0.01 s
Time Delay 2:	0.00 to 1.00 s in steps of 0.01 s
Current Supervision Dropout:	97 to 98% of pickup
Current Supervision Accuracy:	per CT input
Reset Time:	<14 ms typical at 2 x pickup at 60 Hz <16 ms typical at 2 x pickup at 50 Hz
Timing Accuracy:	0 to 1 cycle (Timer 1, Timer 2)

BREAKER TRIP COUNTER	
Trip Counter Limit (Pickup):	1 to 10000 in steps of 1

CT FAILURE (60CTS)	
Inputs:	Neutral Current IN, Neutral Current VN (from three-phase VTs) Ground Current Ig
Time Delay:	0.00 to 60.00 s in steps of 0.01 s
3IO level accuracy:	per CT inputs
3VO level accuracy:	per VT inputs
GND current level accuracy:	see the specifications for phase and ground current inputs
Operate Time:	< 30 ms @ 60 Hz (3I0 > 1.1xPKP, No time delay) < 35 ms @ 50 Hz (3I0 > 1.1xPKP, No time delay)

EMERGENCY RESTART	
Function:	Defeats all motor start inhibit features, resets all trips and alarms, and discharges the thermal capacity to zero so that a hot motor can be restarted in the event of an emergency
Operation:	Contact Input 1 to 10, Virtual Input 1 to 32, Logic Element 1 to 16, Remote Input 1 to 32

LOCKOUT RESET	
Function:	Reset any lockout trips when this feature is configured
Operation:	Contact Input 1 to 10, Virtual Input 1 to 32, Logic Element 1 to 16, Remote Input 1 to 32

RESET	
Function:	Resets any alarms and non-lockout trips when LOCKOUT RESET is configured, or resets any alarms and trips (lockout and non-lockout trips) when LOCKOUT RESET is not configured.
Operation:	Contact Input 1 to 10, Virtual Input 1 to 32, Logic Element 1 to 16, Remote Input 1 to 32

AMBIENT TEMPERATURE	
High Temperature Pickup:	20°C to 80°C in steps of 1°C
Low Temperature Pickup:	-40°C to 20°C in steps of 1°C
Time Delay:	1 to 60 min in steps of 1 mins
Temperature Dropout:	Configurable 90 to 98% of pickup
Temperature Accuracy:	±10°C
Timing Accuracy:	±1 second

BREAKER HEALTH	
Timer Accuracy:	± 3% of delay setting or ± 1 cycle (whichever is greater) from pickup to operate

DEMAND	
Measured Values:	Phase A/B/C present and maximum current, three-phase
present and maximum real/ reactive/apparent power Measurement Type	Thermal Exponential, 90% response time (programmed): 5, 10, 15, 20, 30 minutes
Block Interval / Rolling Demand, time interval (programmed):	5, 10, 15, 20, 30 minutes
Current Pickup Level:	10 to 10000 in steps of 1 A
Real Power Pickup Level:	0.1 to 300000.0 in steps of 0.1 kW
Reactive Power Pickup Level:	0.1 to 300000.0 in steps of 0.1 kVar
Apparent Power Pickup Level:	0.1 to 300000.0 in steps of 0.1 kVA
Dropout Level:	96-98% of Pickup level
Level Accuracy:	± 2%

CONTACT INPUTS	
Inputs:	10
Selectable thresholds:	17, 33, 84, 166 VDC
Tolerance:	±10%
Recognition time:	1/2 cycle
Debounce time:	1 to 64 ms, selectable, in steps of 1 ms
Maximum input voltage & continuous current draw	300 VDC, 2 mA, connected to Class 2 source
Type:	opto-isolated inputs
External switch:	wet contact

CBCT INPUT (50:0.025)	
Range:	0.5 to 15.0 A
Nominal frequency:	50 or 60 Hz
Accuracy (CBCT):	±0.1 A (0.5 to 3.99 A) ±0.2 A (4.0 A to 15 A)

PHASE VOLTAGE INPUTS	
Source VT:	100 to 20000 V
VT secondary range:	50 to 240 V
VT ratio:	1 to 300 in steps of 1
Nominal frequency:	50/60 Hz
Accuracy:	±1.0% throughout range
Voltage withstand:	260 VAC continuous

PHASE & GROUND CURRENT INPUTS	
CT Primary:	30 to 1500 A
Range:	0.02 to 20 × CT
Input type:	1 A or 5 A (must be specified with order)
Nominal frequency:	50/60 Hz
Burden:	<0.1 VA at rated load
Accuracy:	±1% of reading at 1× CT ±3% of reading from 0.2 to 20 × CT ±20% of reading from 0.05 to 0.19 × CT
CT withstand:	1 second at 100 × rated current 2 seconds at 40 × rated current continuous at 3 × rated current

FREQUENCY	
Accuracy:	±0.05 Hz
Resolution:	0.01 Hz
Range:	40.00 to 70.00 Hz

RTD INPUTS	
RTD Type:	100 Ohm platinum (DIN.43760)
RTD Sensing Current:	5 mA
Isolation:	2 kV from base unit (RMIO only)
Distance:	250 m maximum
Range:	-50 to +250°C
Accuracy:	±3°C
Lead Resistance:	25 Ohm max per lead
RTD Trouble Alarm	<-50 or >250 °C
RTD Inputs Available	3 with INPUT/OUTPUT option 'R' installed OR 12 maximum with the RMIO option connected

FORM-A VOLTAGE MONITOR	
Applicable voltage:	20 to 250 VDC
Trickle current:	1 to 2.5 mA

FORM-A RELAYS	
Configuration:	2 (two) electromechanical (one if internal RTD is selected)
Contact material:	silver-alloy
Operate time:	<8 ms
Continuous current:	10 A
Make and carry for 0.2s:	30 A per ANSI C37.90
Break (DC inductive, L/R=40 ms):	24 V / 1 A 48 V / 0.5 A 125 V / 0.3 A 250 V / 0.2 A
Break (DC resistive):	24 V / 10 A 48 V / 6 A 125 V / 0.5 A 250 V / 0.3 A
Break (AC inductive):	720 VA @ 250 VAC Pilot duty A300
Break (AC resistive):	277 VAC / 10 A

TRIP / CLOSE SEAL-IN	
Relay 1 trip seal-in:	0.00 to 9.99 s in steps of 0.01
Relay 2 close seal-in:	0.00 to 9.99 s in steps of 0.01

HIGH RANGE POWER SUPPLY	
Nominal:	120 to 240 VAC 125 to 250 VDC
Range:	60 to 300 VAC (50 and 60 Hz) 84 to 250 VDC
Ride-through time:	35 ms

LOW RANGE POWER SUPPLY	
Nominal:	24 to 48 VDC
Range:	20 to 60 VDC

ALL RANGES	
Voltage withstand:	2 × highest nominal voltage for 10 ms
Power consumption:	15 W nominal, 20 W maximum 20 VA nominal, 28 VA maximum
Fuse rating:	5A fuse; time lag, slow blow, 350V 4.5 O.D. X 14.5mm

METERING SPECIFICATIONS			
Parameter	Accuracy	Resolution	Range
3-Phase Real Power (kW)	±1% of full scale	0.1 MW	±100000.0 kW
3-Phase Reactive Power (kvar)	±1% of full scale	0.1 Mvar	±100000.0 kvar
3-Phase Apparent Power (kVA)	±1% of full scale	0.1 MVA	100000.0 kVA
3-Phase Positive Watthour (MWh)	±1% of full scale	±0.001 MWh	50000.0 MWh
3-Phase Negative Watthour (MWh)	±1% of full scale	±0.001 MWh	50000.0 MWh
3-Phase Positive Varhour (Mvarh)	±1% of full scale	±0.001 Mvarh	50000.0 Mvarh
3-Phase Negative Varhour (Mvarh)	±1% of full scale	±0.001 Mvarh	50000.0 Mvarh
Power Factor	±0.05	0.01	-0.99 to 1.00
Frequency	±0.05 Hz	0.01 Hz	40.00 to 70.00 Hz

Technical Specifications

FORM-C RELAYS	
Configuration:	5 (five) electromechanical (three if internal RTD is selected)
Contact material:	silver-alloy
Operate time:	<8 ms
Continuous current:	10 A
Make and carry for 0.2s:	30 A per ANSI C37.90
Break (DC inductive, L/R=40 ms):	24 V / 1 A 48 V / 0.5 A 125 V / 0.3 A 250 V / 0.2 A
Break (DC resistive):	24 V / 10 A 48 V / 6 A 125 V / 0.5 A 250 V / 0.3 A
Break (AC inductive):	720 VA @ 250 VAC Pilot duty A300
Break (AC resistive):	277 VAC / 10 A

SERIAL	
RS485 port:	Opto-coupled
Baud rates:	up to 115 kbps
Response time:	1 ms typical
Parity:	None, Odd, Even
Maximum Distance:	1200 m (4000 feet)
Isolation:	2 kV
Protocol:	Modbus RTU, DNP 3.0, IEC 60870-5-103

ETHERNET (COPPER)	
Modes:	10/100 MB (auto-detect)
Connector:	RJ-45
Protocol:	Modbus TCP/IP, DNP 3.0, IEC 60870-5-104, IEC 61850 GOOSE, IEC 61850

ETHERNET (FIBER)	
Fiber type:	100 MB Multi-mode
Wavelength:	1300 nm
Connector:	MTRJ
Transmit power:	-20 dBm
Receiver sensitivity:	-31 dBm
Power budget:	9 dB
Maximum input power:	-11.8 dBm
Typical distance:	2 km (1.25 miles)
Duplex:	half/full
Protocol:	Modbus TCP/IP, DNP 3.0, IEC 60870-5-104, IEC 61850 GOOSE, IEC 61850

USB	
Standard specification:	Compliant with USB 2.0
Data transfer rate:	115 kbps

CAN (RMIO)	
Maximum distance:	250 m (820 feet)
Cable type:	Shielded or unshielded twisted pair
Cable gauge	Belden 9841 or similar 24 AWG for distances up to 100 m; 22 AWG for distances up to 250 m

DIMENSIONS	
Size:	Refer to Dimensions section
NON-DRAWOUT UNIT	
Weight (net):	2.9 kg (6.4 lbs)
Weight (gross):	4.0 kg (8.6 lbs)
DRAWOUT UNIT	
Weight (net):	3.9 kg (8.6 lbs)
Weight (gross):	5.0 kg (11.0 lbs)

CERTIFICATION	
	Applicable council directive according to low voltage directive 2014/35/EU
CE:	EMC Directive 2014/30/EU, UL508
ISO:	Manufactured under a registered quality program ISO9001
EAC:	Machines and Equipment TR CU 010/2011
LLOYD's Register	Rules and regulations for the classifications of Ships
Marine applications	ENV2, ENV3

EAC	
The EAC Technical Regulations (TR) for Machines and Equipment apply to the Customs Union (CU) of the Russian Federation, Belarus, and Kazakhstan	
Country of origin	Spain or Canada; see label on the unit
Date of manufacture	See label on the side of the unit
Declaration of Conformity and/ or Certificate of Conformity	Available upon request

TYPE TESTS		
Dielectric voltage withstand	(high voltage power supply) 2200 VAC for one second (low voltage power supply) 550 VAC for one second	
Impulse voltage withstand:	EN60255-5	5KV
Insulation resistance	500VDC >100mohm	
Damped Oscillatory:	IEC 61000-4-18/ IEC 60255-22-1	2.5KV CM, 1KV DM
Electrostatic Discharge:	EN61000-4-2/ IEC 60255-22-2	Level 4
RF immunity:	EN61000-4-3/ IEC 60255-22-3	Level 3
Fast Transient Disturbance:	EN61000-4-4/ IEC60255-22-4	Level 4
Surge Immunity:	EN61000-4-5/ IEC 60255-22-5	Level 3 & 4
Conducted RF Immunity:	EN61000-4-6/ IEC 60255-22-6	Level 3
Power Frequency Magnetic Field Immunity:	IEC 61000-4-8	Level 4
Radiated & Conducted Emissions:	CISPR11 /CISPR22/ IEC 60255-25	Class A
Sinusoidal Vibration:	IEC 60255-21-1	Class 1
Voltage Dip & interruption:	IEC 61000-4-11	0, 40, 70, 80% dips, 250/ 300 cycle interrupts
Ingress Protection:	IEC 60529	IP40 front , IP10 Back
Environmental (Cold):	IEC 60068-2-1	-20C 16 hrs
Environmental (Dry heat):	IEC 60068-2-2	85C 16hrs
Relative Humidity Cyclic:	IEC 60068-2-30	6day variant 2
Fast Transient Disturbance:	IEEE C37.90.1	4KV CM & DM
SWC Damped Oscillatrory:	IEEE C37.90.1	2.5KV CM & DM
RF Immunity	IEEE C37.90.2	20V/m 80-1Ghz 35V/m max at 80% modulation
Electrostatic Discharge:	IEEE C37.90.3	8KV CD, 15KV AD

OPERATING ENVIRONMENT	
Ambient operating temperature:	–40°C to +60°C [-40°F to +140°F]
Ambient storage / shipping temperature:	–40°C to +85°C [-40°F to +185°F]
Humidity:	Operating up to 95% (non condensing) @ 55C (As per IEC 60068-2-30 Variant 2, 6days)
Altitude:	2000 m (max)
Pollution degree:	II
Overvoltage category:	III
Ingress Protection:	IP42 Front , IP10 back (IP20 cover is available for drawout version)
Noise:	0 dB

Ordering

	339	-	*	*	*	*	*	S	N	*	*	*	*	*	Description
Interface	339														339 Motor Protection System
Language[a]		E													English without programmable LEDs
		L													English with programmable LEDs
Phase Currents[b]			P0												1 A and 5 A configurable phase current inputs
			P1												1 A 3-phase current inputs
			P5												5 A 3-phase current inputs
Ground Currents[c]				G0											1 A and 5 A configurable ground current input
				G1											1 A ground current input
				G5											5 A ground current input
Power Supply					L										24 to 48 V DC
					H										110 to 250 V DC/110 to 230 V AC
Input/Output[d]						E									10 Contact Inputs, 7 Outputs (2 Form A, 5 Form C)
						R									10 Contact Inputs, 4 Outputs (1 Form A, 3 Form C),3 100 Ohm Platinum RTD Inputs
Current Protection							S								Standard configuration: 37, 46, 48, 49, 50P(1), 50G/SG(1), 50N(1), 50L,51R, 66, 86, 51N(1), 51P(1), 50BF
Other Options										N					No Selection
										M					Voltage, Power, Energy Metering, VTFF (1), 60CTS
										P					Voltage Protection: 37P, 27P(2), 27P_1(2), 47(1), VTFF(1), 59P(2), 81O(2), 81U(2), 59_2(1), 67N(1), 32(2), 60CTS
Communications											S	N			Standard: Front USB, Rear RS485: Modbus RTU, DNP3.0, IEC60870-5-103
											1	E			Standard + Ethernet (Copper + Fiber - MTRJ) Modbus TCP/IP, DNP3.0, IEC 60870-5-104
											2	E			Standard + Ethernet (Copper + Fiber - MTRJ) Modbus TCP/IP, DNP3.0, IEC 60870-5-104, IEC 61850 GOOSE
											3	E			Standard + Ethernet (Copper + Fiber - MTRJ) Modbus TCP/IP, DNP3.0, IEC 60870-5-104, IEC 61850
Case Design													D		Protection Relay with drawout design
													N		Protection Relay with non-drawout design
Harsh Environment														N	None
														H	Harsh Environment Conformal Coating

Ordering Notes:

a. The Language option "L" is only available with the drawout Case Design "D".
b. Phase current option "P0" and Ground current option "G0" is only available on the non-drawout version (Case Design option "N")
c. Ground current options "G0/G1/G5" must match the corresponding "P0/P1/P5" Phase currents
d. The Input/Output option "R" is only available on the drawout version (Case Design option D)

Accessories for the 339

- SR3 Depth Reducing Collar Kit – 1.375 18L0-0075
- SR3 Depth Reducing Collar Kit – 3.00 18L0-0076
- 18L0-0080 SR3 IP20 Kit

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Grid Solutions

650 Markland St.
Markham, ON
Canada L6C 0M1

Toll Free (NA Only): 1-800-547-8629
Tel: 905-927-7070
Fax: 905-927-5098

GEGridSolutions.com

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